

Chapter 3 Optimization

3.1 Dimensional reduction of the multivariate data

3.2 Eigenvalue and eigenvector

3.3 Spectral decomposition

3.4 Matrix decomposition in R and SAS/IML

3.5 Geometric concepts of positive definite symmetric matrix

Key-words

- Lagrange multiplier
- Eigenvalue and eigenvector
- Characteristic polynomial
- SD(Spectral Decomposition) and SVD(Singular Value Decomposition)

3.1 Dimensional reduction of the multivariate data

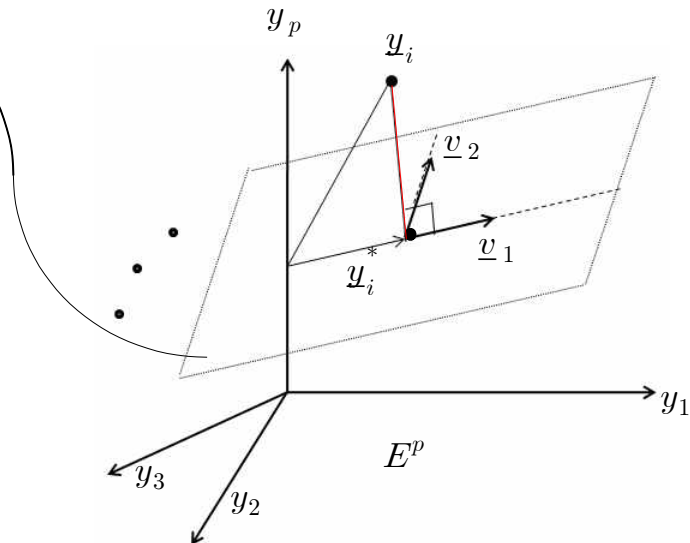
$$X_{n \times p} = (x_{ij}) \Rightarrow Y = (y_{ij}) = (x_{ij} - \bar{x}_j) = \begin{pmatrix} \underline{y}_1^t \\ \vdots \\ \underline{y}_i^t \\ \vdots \\ \underline{y}_n^t \end{pmatrix}, \quad \underline{y}_i^t = (x_{i1} - \bar{x}_1, \dots, x_{ip} - \bar{x}_p)$$

$$\Leftrightarrow \underline{y}_i = \begin{pmatrix} x_{i1} - \bar{x}_1 \\ \vdots \\ x_{ip} - \bar{x}_p \end{pmatrix} = \begin{pmatrix} y_{i1} \\ \vdots \\ y_{ip} \end{pmatrix}, \quad i = 1, 2, \dots, n \in E^p$$

$\exists E^s = \text{span}(\underline{v}_1, \underline{v}_2, \dots, \underline{v}_s)$ and $\underline{y}_i^*$: projection of n points $\underline{y}_i$ onto the vectors $\underline{v}_1, \dots, \underline{v}_s \in E^s$

$$\Rightarrow \min \sum_{i=1}^n \|\underline{y}_i - \underline{y}_i^*\|^2$$

$$\text{with } \underline{v}_j^t \underline{v}_k = 0, \quad \underline{v}_j^t \underline{v}_j = 1 \equiv \|\underline{v}_j\|$$



Projection: Projection $\underline{y}_i^*$ of the n points $\underline{y}_i, i = 1, \dots, n$ onto the vector $\underline{v}$.

$$\underline{y}_i^* = k\underline{v}_{p \times 1},$$

$$\underline{r}_i = \underline{y}_i - \underline{y}_i^* : \text{residual vector}$$

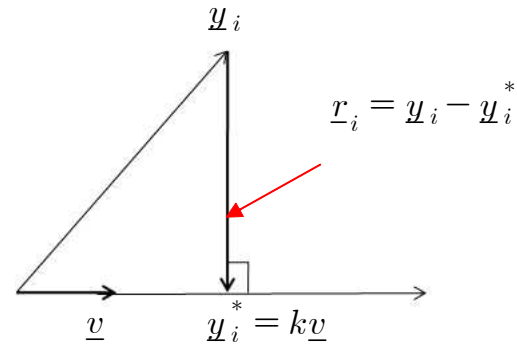
$$\underline{r}_i \perp \underline{v} \Leftrightarrow \underline{r}_i \cdot \underline{v} = 0$$

$$\Leftrightarrow (\underline{y}_i - k\underline{v})^t \underline{v} = 0$$

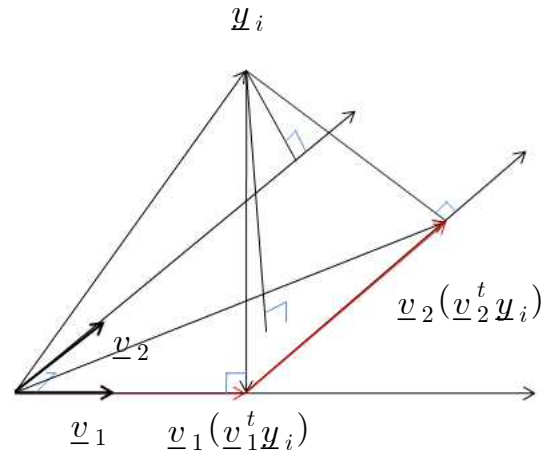
$$\Leftrightarrow k = \frac{\underline{y}_i^t \underline{v}}{\underline{v}^t \underline{v}} = \underline{y}_i^t \underline{v} \quad (\because \|\underline{v}\| = 1)$$

$$= \underline{v}^t \underline{y}_i$$

$$\therefore \underline{y}_i^* \equiv \underline{v} (\underline{v}^t \underline{y}_i)$$



Projection of $\underline{y}_i$ onto a one-dimensional subspace



Projection of $\underline{y}_i$ onto a s -dimensional subspace

$$\begin{aligned} \therefore \underline{y}_i^* &= \underline{v}_1(\underline{v}_1^t \underline{y}_i) + \underline{v}_2(\underline{v}_2^t \underline{y}_i) + \dots + \underline{v}_s(\underline{v}_s^t \underline{y}_i) = \sum_{k=1}^s \underline{v}_k \underline{v}_k^t \underline{y}_i \\ &= VV^t \underline{y}_i \quad \text{where } V = (\underline{v}_1, \dots, \underline{v}_s) \end{aligned}$$

$$\underline{y}_i - \underline{y}_i^* = \underline{y}_i - VV^t \underline{y}_i = (I_p - VV^t) \underline{y}_i$$

$$\| \underline{y}_i - \underline{y}_i^* \|^2 = (\underline{y}_i - \underline{y}_i^*)^t (\underline{y}_i - \underline{y}_i^*)$$

$$= \underline{y}_i^t (I_p - VV^t) (I_p - VV^t) \underline{y}_i$$

$$= \underline{y}_i^t (I_p - VV^t) \underline{y}_i \quad \left(\because (I_p - VV^t)^t (I_p - VV^t) = (I_p - VV^t) \right)$$

$$\begin{aligned}
\therefore S &= \sum_{i=1}^n \underline{y}_i^t (I_p - VV^t) \underline{y}_i \\
&= \sum_{i=1}^n [\underline{y}_i^t \underline{y}_i - \underline{y}_i^t VV^t \underline{y}_i] \\
&= \sum_{i=1}^n \text{tr} [\underline{y}_i^t \underline{y}_i - \underline{y}_i^t VV^t \underline{y}_i] \\
&= \sum_{i=1}^n \text{tr} [\underline{y}_i \underline{y}_i^t - V^t \underline{y}_i \underline{y}_i^t V] \\
&= \text{tr} \left[\sum_{i=1}^n \underline{y}_i \underline{y}_i^t - V^t \sum_{i=1}^n \underline{y}_i \underline{y}_i^t V \right] \\
&= \text{tr} [Y^t Y - V^t Y^t Y V] \\
&= \sum_{i=1}^n \underline{y}_i^t \underline{y}_i - \sum_{k=1}^s \underline{v}_k^t Y^t Y \underline{v}_k \\
\therefore S &= \sum_{i=1}^n \underline{y}_i^t \underline{y}_i - \sum_{k=1}^s \underline{v}_k^t Y^t Y \underline{v}_k
\end{aligned}$$

$$\min_{\underline{v}_k} S \Leftrightarrow \max_{\underline{v}_k} \sum_{k=1}^s \underline{v}_k^t Y^t Y \underline{v}_k$$

■ Optimal problem in dimensional reduction of multivariate data

$\underline{y}_i^* = \underline{v}_k(\underline{v}_k^t \underline{y}_i)$: Projection of the n points $\underline{y}_i, i = 1, \dots, n$
onto the basis vector $\underline{v}_k$ of k th dimensional subspace.

All at once, it is impossible to obtain all $\underline{v}_k, k = 1, \dots, p$.

Subsequently, it is possible to find $\underline{v}_k$.

Therefore consider the optimal problem of maximizing $\underline{v}^t Y^t Y \underline{v}$ for any $\underline{v}$ s.t. $\underline{v}^t \underline{v} = 1$.

This optimal problem in dimensional reduction of multivariate data can be solved by

Lagrange multipliers method

$$f(\underline{v}, \lambda) = \underline{v}^t Y^t Y \underline{v} - \lambda(\underline{v}^t \underline{v} - 1)$$

$$\frac{\partial f}{\partial \underline{v}} = 2 Y^t Y \underline{v} - 2 \lambda \underline{v} = 0 \Leftrightarrow Y^t Y \underline{v} = \lambda \underline{v} : \text{Eigenvalue-eigenvector equation}$$

3.2 Eigenvalue and eigenvector

■ Definition of eigenvalue and eigenvector

Given a $A_{p \times p}$,

eigenvalue-eigenvector equation: $A\underline{v} = \lambda\underline{v} \Rightarrow \lambda$: eigenvalues

$\underline{v}(\neq \underline{0})$: eigenvector corresponding to λ

Note

$$A\underline{v} - \lambda\underline{v} = \underline{0} \Leftrightarrow (A - \lambda I)\underline{v} = \underline{0}$$

- $A - \lambda I$: non-singular $\Leftrightarrow |A - \lambda I| \neq 0 \Leftrightarrow \exists (A - \lambda I)^{-1} \Rightarrow \underline{v} = \underline{0}$ (contradiction!)
- $A - \lambda I$: singular $\Rightarrow \underline{v} = [(A - \lambda I)^-(A - \lambda I) - I]\underline{z}$ for arbitrary $\underline{z}$

Result

$$\exists \lambda(\text{eigenvalue}) \Rightarrow |A - \lambda I| = 0 : \text{Characteristic(determinantal) equation of } A$$

Example 1

$$A = \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \lambda \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow \begin{pmatrix} 1-\lambda & 1 \\ -2 & 4-\lambda \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \begin{vmatrix} 1-\lambda & 1 \\ -2 & 4-\lambda \end{vmatrix} = 0 &\Leftrightarrow (1-\lambda)(4-\lambda) + 2 = 4 - 5\lambda + \lambda^2 + 2 \\ &= \lambda^2 - 5\lambda + 6 \\ &= (\lambda - 3)(\lambda - 2) = 0 \\ &\Leftrightarrow \lambda = 3 \text{ or } \lambda = 2 \end{aligned}$$

$$\text{i) } \lambda = 2 \Rightarrow \begin{pmatrix} -1 & 1 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow -v_1 + v_2 = 0 \Leftrightarrow v_1 = v_2: \text{ arbitrary}$$

$$\therefore \underline{v} = k(1, 1)^t, \quad k: \text{ constant}$$

$$\text{ii) } \lambda = 3 \Rightarrow \begin{pmatrix} -2 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow -2v_1 + v_2 = 0 \Leftrightarrow v_2 = 2v_1$$

$$\therefore \underline{v} = k(1, 2)^t, \quad k: \text{ constant}$$

Example 2: complex eigenvalues and eigenvectors

$$A = \begin{pmatrix} 1 & 1 \\ -2 & -1 \end{pmatrix}$$

$$\begin{vmatrix} 1-\lambda & 1 \\ -2 & -1-\lambda \end{vmatrix} = -(1-\lambda)(1+\lambda) + 2$$

$$= \lambda^2 + 1 = 0$$

$$\therefore \lambda = \pm \sqrt{-1} = \pm i$$

$$\text{i) } \lambda = i \Rightarrow \begin{pmatrix} 1 & 1 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = i \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow \begin{cases} v_1 + v_2 = i v_1 \\ -2v_1 - v_2 = i v_2 \end{cases} \Leftrightarrow -2v_1 = (1+i)v_2$$

$$\Leftrightarrow v_1 = \frac{-(1+i)v_2}{2}, v_2 = -2k \Rightarrow \underline{v} = k \begin{pmatrix} 1+i \\ -2 \end{pmatrix}, k \neq 0$$

$$\text{ii) } \lambda = -i \Rightarrow \begin{pmatrix} 1 & 1 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = -i \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Leftrightarrow \begin{cases} v_1 + v_2 = -i v_1 \\ -2v_1 - v_2 = -i v_2 \end{cases} \Leftrightarrow -2v_1 = (1-i)v_2$$

$$\Leftrightarrow v_1 = \frac{-(1-i)v_2}{2}, v_2 = -2k \Rightarrow \underline{v} = k \begin{pmatrix} 1-i \\ -2 \end{pmatrix}, k \neq 0$$

Example 3

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 2 & 3 & 4 \\ -1 & -1 & -2 \end{pmatrix}$$

$$\begin{vmatrix} 2-\lambda & 1 & 1 \\ 2 & 3-\lambda & 4 \\ -1 & -1 & -2-\lambda \end{vmatrix} = (2-\lambda)(3-\lambda)(-2-\lambda) - 2 - 4 - \{-(3-\lambda) + 2(-2-\lambda) - 4(2-\lambda)\}$$

$$= (\lambda+1)(\lambda-1)(\lambda-3) = 0$$

$$\therefore \lambda = -1 \text{ or } \lambda = 1 \text{ or } \lambda = 3$$

$$\text{i) } \lambda = -1 \Rightarrow \begin{pmatrix} 3 & 1 & 1 \\ 2 & 4 & 4 \\ -1 & -1 & -1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \underline{0} \Leftrightarrow \begin{cases} 3v_1 + v_2 + v_3 = 0 \\ 2v_1 + 4v_2 + 4v_3 = 0 \\ -v_1 - v_2 - v_3 = 0 \end{cases} \Rightarrow \begin{matrix} v_1 = 0 \\ v_2 = -v_3 \\ v_3 = -v_2 \end{matrix}$$

$$\Leftrightarrow v_1 = 0, v_2 = k, v_3 = -k \Rightarrow \underline{v} = k \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

$$\text{ii) } \lambda = 1 \Rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 4 \\ -1 & -1 & -3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \underline{0} \Leftrightarrow \begin{cases} v_1 + v_2 + v_3 = 0 \\ v_1 + v_2 + 2v_3 = 0 \\ v_1 + v_2 + 3v_3 = 0 \end{cases} \Rightarrow \begin{cases} v_1 = -v_2 \\ v_2 = -v_1 \\ v_3 = 0 \end{cases}$$

$$\Leftrightarrow v_1 = k, v_2 = -k, v_3 = 0 \Rightarrow \underline{v} = k \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

$$\text{iii) } \lambda = 3 \Rightarrow \begin{pmatrix} -1 & 1 & 1 \\ 2 & 0 & 4 \\ -1 & -1 & -5 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \underline{0} \Leftrightarrow \begin{cases} v_1 - v_2 - v_3 = 0 \\ v_1 + 2v_3 = 0 \\ v_1 + v_2 + 5v_3 = 0 \end{cases} \Rightarrow \begin{cases} v_1 = -2v_3 \\ v_2 = -3v_3 \\ v_3 = v_1 - v_2 = -\frac{1}{3}v_2 \end{cases}$$

$$\Leftrightarrow v_1 = -2k, v_2 = -3k, v_3 = k \Rightarrow \underline{v} = k \begin{pmatrix} -2 \\ -3 \\ 1 \end{pmatrix}$$

Example 4

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix}$$

$$\begin{vmatrix} 1-\lambda & 2 & 3 \\ 0 & 1-\lambda & 0 \\ 0 & 2 & 1-\lambda \end{vmatrix} = (1-\lambda)^3 = 0$$

$$\therefore \lambda = 1 \Rightarrow \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = 0 \Leftrightarrow \begin{cases} 2v_2 + 3v_3 = 0 \\ 2v_2 = 0 \end{cases} \Rightarrow \begin{matrix} v_2 = 0 \\ v_3 = 0 \end{matrix}$$

$$\Rightarrow \underline{v} = k \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \left\{ \begin{pmatrix} k \\ 0 \\ 0 \end{pmatrix} : |k| < \infty \right\} = S_A(1) : \text{Eigenspace}$$

Note : Eigenspace of A associated with λ

$$S_A(\lambda) \equiv \{ \underline{x} : \underline{x} \in R^m \wedge A\underline{x} = \lambda \underline{x} \}$$

: Collection of all eigenvectors corresponding to the particular eigenvalue λ along with the trivial vector $\underline{0}$

Remark: Eigenvalue–eigenvector equation of A^{-1}

A : non-singular, $A\underline{v} = \lambda \underline{v}$

$$\exists A^{-1} \Rightarrow A^{-1}A\underline{v} = \lambda A^{-1}\underline{v} \Leftrightarrow \underline{v} = \lambda A^{-1}\underline{v} \Leftrightarrow A^{-1}\underline{v} = \lambda^{-1}\underline{v}$$

$\Rightarrow \lambda^{-1}$: eigenvalue of A^{-1} corresponding to the eigenvector $\underline{v}$

3.3 Spectral decomposition

■ Spectral Decomposition (SD) of a symmetric matrix

Given a $p \times p$ symmetric matrix A with eigenvalues $\lambda_1, \dots, \lambda_p$ and

$\{\underline{v}_1, \dots, \underline{v}_p\}$ is a set of orthonormal eigenvectors corresponding to these eigenvalues

$$\Rightarrow A = VD_\lambda V^t$$

where $D_\lambda = \text{diag}(\lambda_1, \dots, \lambda_p)$ and $V = (\underline{v}_1, \dots, \underline{v}_p)$ st $V^t V = VV^t = I$.

Note

$$\text{Orthonormal} \Leftrightarrow \begin{cases} \|\underline{v}_j\| = 1 \\ \underline{v}_j^t \underline{v}_k = 0 \end{cases}$$

Corollary

i) $A^{1/2}$: square root matrix of A satisfying $A = A^{1/2} A^{1/2} > 0$

- $D_{\sqrt{\lambda}} = \text{diag}(\lambda_1^{1/2}, \dots, \lambda_p^{1/2})$

- $A^{1/2} = V D_{\sqrt{\lambda}} V^t$: symmetric square root of A

ii) $(A^{1/2})^t = (V D_{\sqrt{\lambda}} V^t)^t = V D_{\sqrt{\lambda}} V^t = A^{1/2}$

Remark

$$Y = (x_{ij} - \bar{x}_j)$$

- $Y = HX$ where $H = I - \frac{1}{n}J$: centering matrix

- $Y^t Y = (n-1)S$ where S : covariance matrix

- $A = Y^t Y = V D_{\lambda} V^t = (n-1)S \Leftrightarrow S = V D_{\lambda/(n-1)} V^t$

■ SVD (Singular Value Decomposition)

Given a $n \times p$ matrix Y ,

$$Y = U D_{\sqrt{\lambda}} V^t$$

$n \times p \quad n \times p \quad p \times p \quad p \times p$

where $D_{\sqrt{\lambda}} = \text{diag}(\sqrt{\lambda_1}, \dots, \sqrt{\lambda_p})$ with $\lambda_1 \geq \dots \geq \lambda_p$: eigenvalues of $Y^t Y (= V D_{\lambda} V^t)$

$$V^t V = V V^t = I, \quad U^t U = I$$

Note: SVD is a factorization for a **matrix of any size**.

SD is a factorization for a **square and symmetric matrix**.

Note : SVD of a $n \times p$ centred data matrix : $Y = (x_{ij} - \bar{x}_j) = U D_{\sqrt{\lambda}} V^t$

$$\begin{aligned} \cdot \quad Y^t Y_{p \times p} &= (U D_{\sqrt{\lambda}} V^t)^t (U D_{\sqrt{\lambda}} V^t) \\ &= V D_{\sqrt{\lambda}} U^t U D_{\sqrt{\lambda}} V^t \\ &= V D_{\lambda} V^t \quad : \text{SD } (= (n-1)S) \end{aligned}$$

$$\begin{aligned}
\bullet \quad YY^t &= (UD_{\sqrt{\lambda}} V^t)(UD_{\sqrt{\lambda}} V^t)^t \\
&= UD_{\sqrt{\lambda}} V^t VD_{\sqrt{\lambda}} U^t \\
&= UD_{\lambda} U^t \quad : \text{SD} \quad (\neq (n-1)S)
\end{aligned}$$

Applications in multivariate statistics

- PCA (Principal Component Analysis)
- FA (Factor Analysis)
- MDS (MultiDimensional Scaling)

etc.

■ GSVD (Generalized Singular Value Decomposition)

$$A = \underset{n \times p}{\tilde{U}} \underset{n \times r}{D_{\sqrt{\lambda}}} \underset{r \times p}{\tilde{X}^t}$$

where $\tilde{U}^t \Omega \tilde{U} = \tilde{V}^t \Phi \tilde{V} = I$, $D_{\sqrt{\lambda}} = \text{diag}(\tilde{\lambda}_1^{1/2}, \dots, \tilde{\lambda}_r^{1/2})$ with $\tilde{\lambda}_1 \geq \dots \geq \tilde{\lambda}_r \geq 0$

$\tilde{U}$: orthonormal w.r.t. $\Omega > 0$

$\tilde{V}$: orthonormal w.r.t. $\Phi > 0$

Note

$$\tilde{U}^t \Omega^{1/2} \Omega^{1/2} \tilde{U} = U^t U$$

$$\tilde{V}^t \Phi^{1/2} \Phi^{1/2} \tilde{V} = V^t V$$

$$\Rightarrow \Omega^{1/2} A \Phi^{1/2} = (\Omega^{1/2} \tilde{U}) D_{\sqrt{\lambda}} \tilde{V}^t \Phi^{1/2} = U D_{\sqrt{\lambda}} V^t$$

Application

Correspondence Analysis

3.4 Matrix decomposition in R and SAS/IML

$A = VD_{\lambda}V^t$: SD and $Z = UD_qV^t$: SVD	
R	SAS/IML
eigen(A) <pre>eigen.A <- eigen(A) round(eigen.A\$values, 4) round(eigen.A\$vectors, 4)</pre>	call eigen(lambda, V, A) <pre>B=V*diag(lambda)*V';</pre>
svd(Z) <pre>svd.Z <- svd(Z) round(svd.Z\$d, 4) round(svd.Z\$u, 4) round(svd.Z\$v, 4)</pre>	call svd(U,q,V,Z) <pre>B=U*diag(q)*V';</pre>

Refer to the pp.69~71 in your text.

3.5 Geometric concept of positive definite symmetric matrix

$$\underline{x} \sim N_p(\underline{\mu}, \Sigma), \quad \Sigma > 0$$

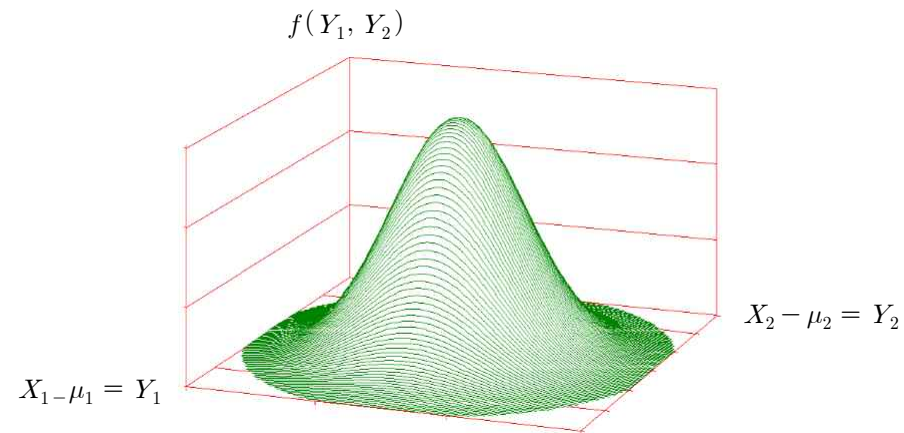
$$f(\underline{x}) = (2\pi)^{-p/2} |\Sigma|^{-1/2} \exp\left(-\frac{1}{2}(\underline{x} - \underline{\mu})^t \Sigma^{-1} (\underline{x} - \underline{\mu})\right)$$

$p = 2$: Bivariate normal distribution

$$N_2(\underline{\mu}, \Sigma), \quad \underline{\mu} = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \quad \Sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{pmatrix}$$

$$\text{let } (\underline{x} - \underline{\mu})^t \Sigma (\underline{x} - \underline{\mu}) = 1$$

$$\Rightarrow \underline{\mu} = 0, \quad \underline{x}^t \Sigma^{-1} \underline{x} = 1$$



Note

$$\text{i) } \Sigma = VD_{\lambda}V^t$$

$$\text{ii) } \Sigma^{-1} = VD_{1/\lambda}V^t \quad (\because V^tV = I)$$

$$\text{iii) } \underline{x}^t \Sigma^{-1} \underline{x} = \underline{x}^t (VD_{1/\lambda}V^t) \underline{x} = 1$$

$$\Leftrightarrow (\underline{x}^t V) D_{1/\lambda} (\underline{x}^t V)^t = 1$$

$$\text{let } V^t \underline{x} = \underline{y} = (y_1, \dots, y_p)^t : \text{pc transformation}$$

$$\Leftrightarrow \underline{y}^t D_{1/\lambda} \underline{y} = 1$$

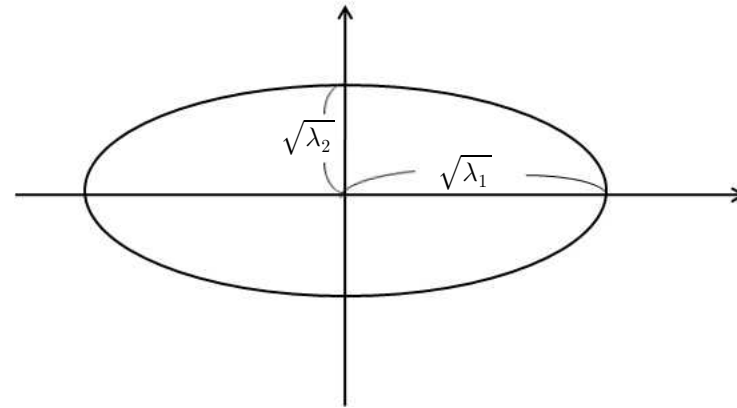
$$\Leftrightarrow (y_1 \dots y_p) \begin{pmatrix} \frac{1}{\lambda_1} & & 0 \\ & \ddots & \\ 0 & & \frac{1}{\lambda_p} \end{pmatrix} \begin{pmatrix} y_1 \\ \vdots \\ y_p \end{pmatrix} = 1$$

$$\Leftrightarrow \frac{y_1^2}{\lambda_1} + \dots + \frac{y_p^2}{\lambda_p} = 1 \quad : \text{The equation of an ellipsoid}$$

- $p = 2$

$$\frac{y_1^2}{\lambda_1} + \frac{y_2^2}{\lambda_2} = 1$$

$$y_1 = \pm \sqrt{\lambda_1}, \quad y_2 = \pm \sqrt{\lambda_2}$$



- $p = 3$

$$\frac{y_1^2}{\lambda_1} + \frac{y_2^2}{\lambda_2} + \frac{y_3^2}{\lambda_3} = 1$$

